

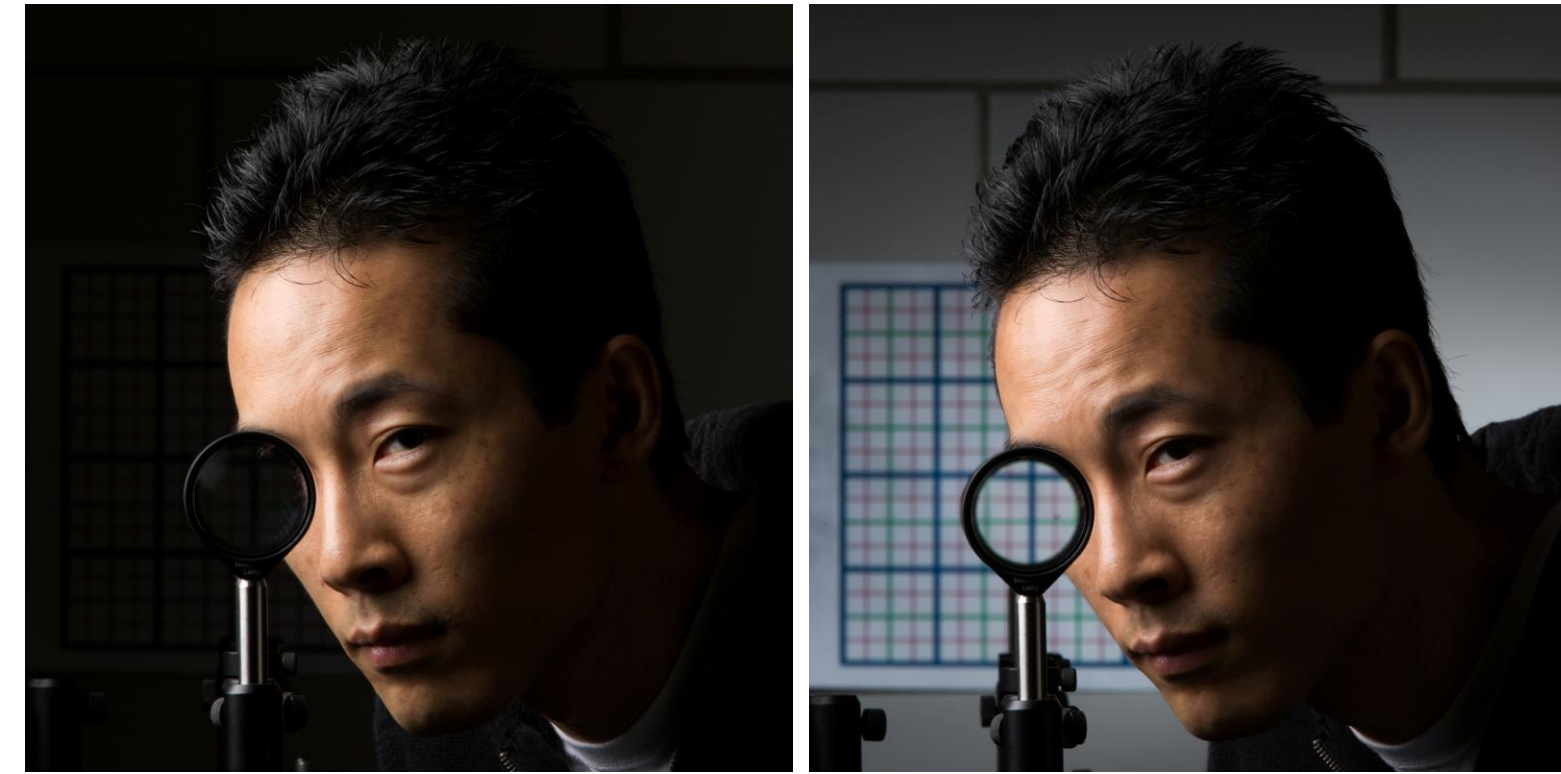
A. Summary

To achieve broadband, omnidirectional invisibility, we propose “digital cloaking,” where space, angle, spectrum, and phase are discretized. Experimentally, we demonstrate a 2D, planar, ray optics, digital cloak by using lenticular lenses. Theoretically, this can extend to a good approximation for an “ideal” cloak. As commercial digital technology improves, a **wearable cloak** is possible in the future [1].

B. “Cloaking”

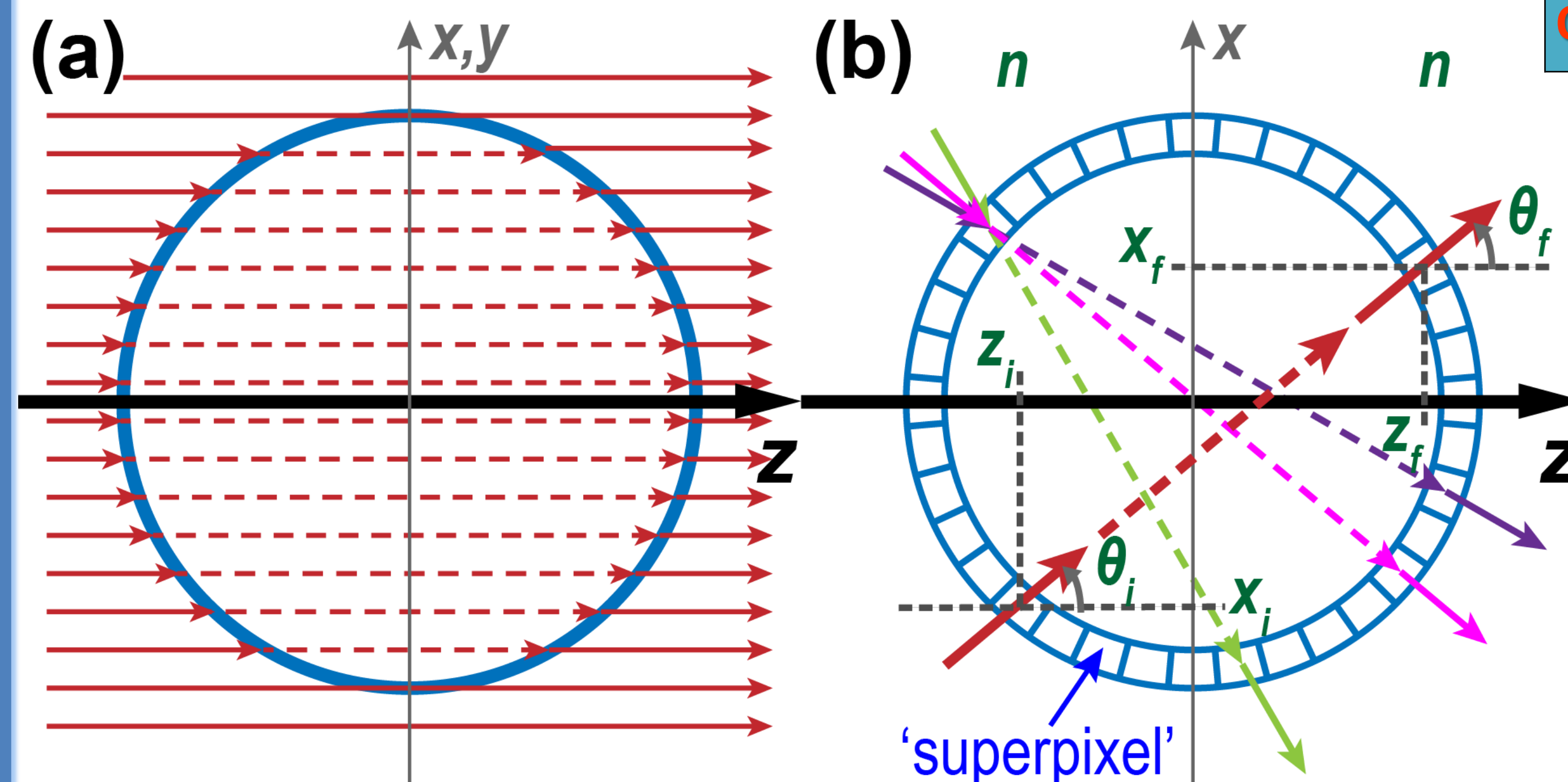
A ‘perfect’ cloak should:

- 1) Hide a non-zero volume,
- 2) Make itself and the hidden object appear transparent.



C. ‘Discretized’ Cloaking [1]

- Consider an ideal spherical cloak (a). Light appears to travel in straight line through cloaked space (dashed arrows).



- Discretize cloak surface space into ‘superpixels’ in (b):

- Can approximate all ideal cloak properties.
- Generalizable to arbitrary or dynamic shape.
- Simplified to pixel-to-pixel light mapping:

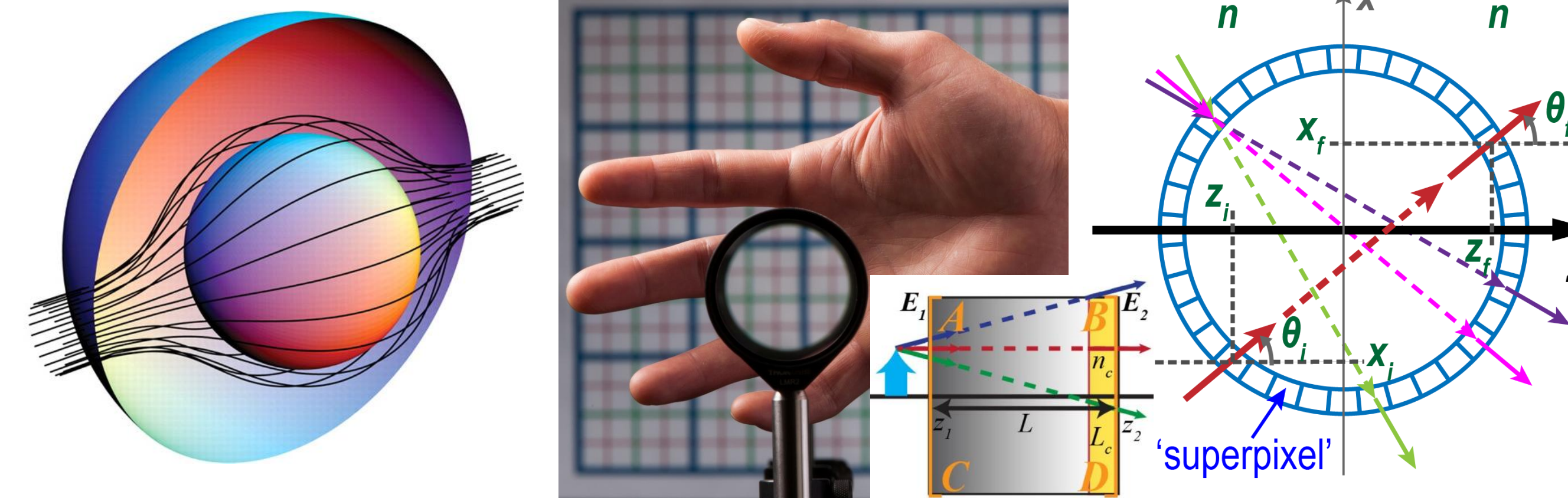
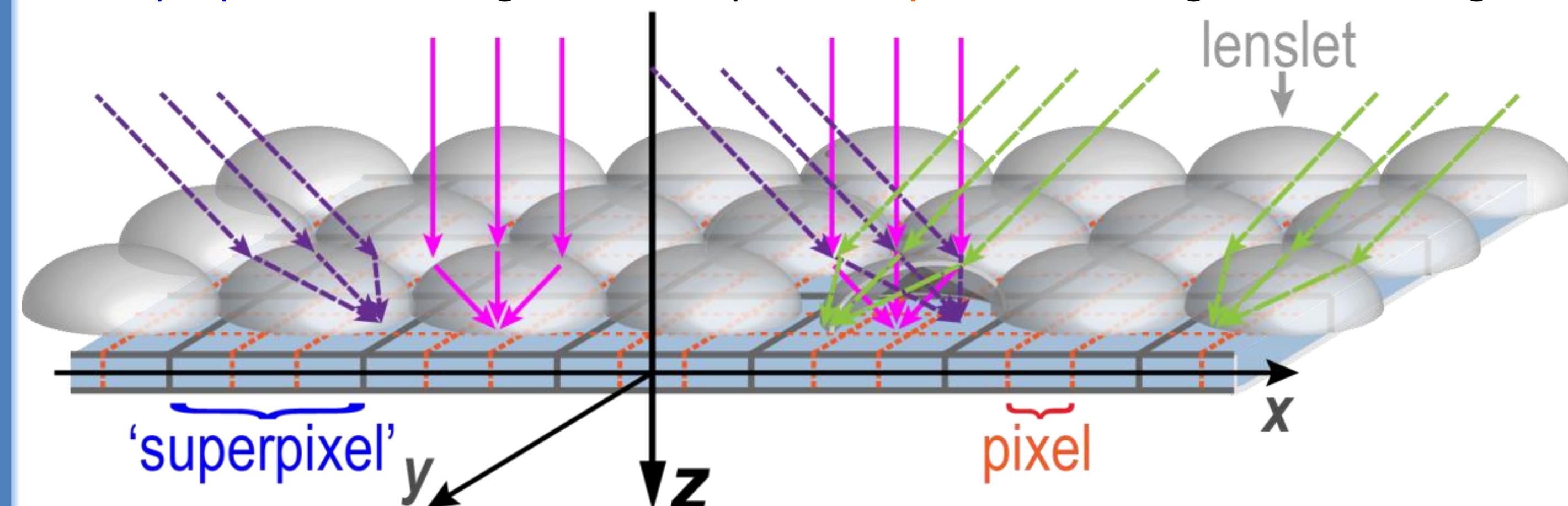
$$\begin{bmatrix} x_f \\ n \tan \theta_f \end{bmatrix}_{z=z_f} = \begin{bmatrix} 1 & (z_f - z_i)/n \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x_i \\ n \tan \theta_i \end{bmatrix}_{z=z_i}$$

D. ‘Digital Integral’ Cloaking [1]

- Because surface discretized:

- **Digital:** Add digital displays, detectors.
- **Integral:** Use lenslet arrays (‘Integral Imaging’ [4]).

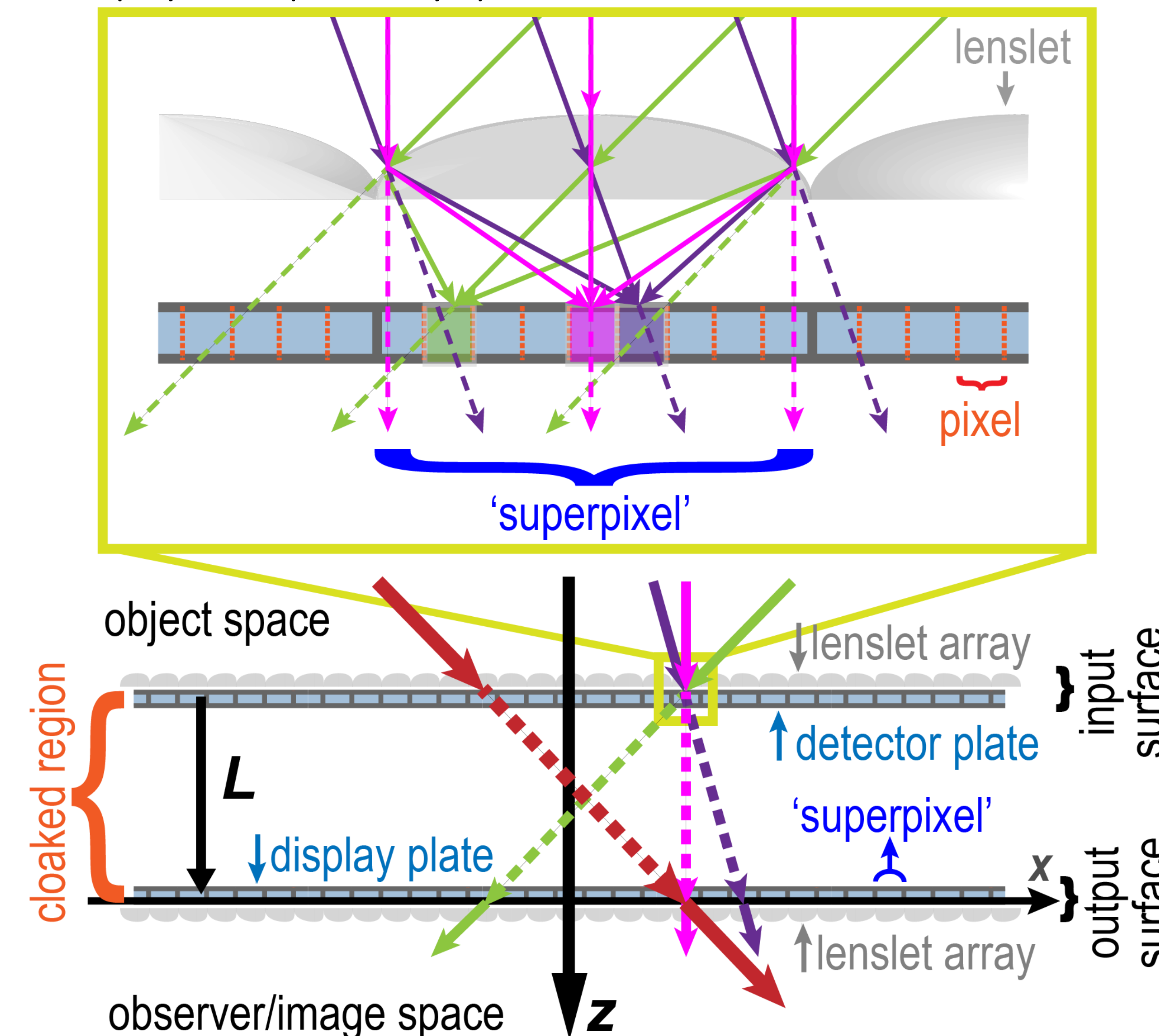
→ **Superpixels** collect light of same position, **pixels** collect light of same angle.



‘Ideal’ Cloak Properties	Transformation Optics ^[2]	Paraxial Cloaking ^[3]	Discretized Cloaking ^[1]
Broadband	Difficult	Excellent	Good
Visible spectrum			
Isotropic			
Macroscopic			
3D	Some challenges		
Full-field (+phase)	Excellent	Broadband (theory)	
Omnidirectional		Continuous multidirection	

E. Example Digital Integral Cloak

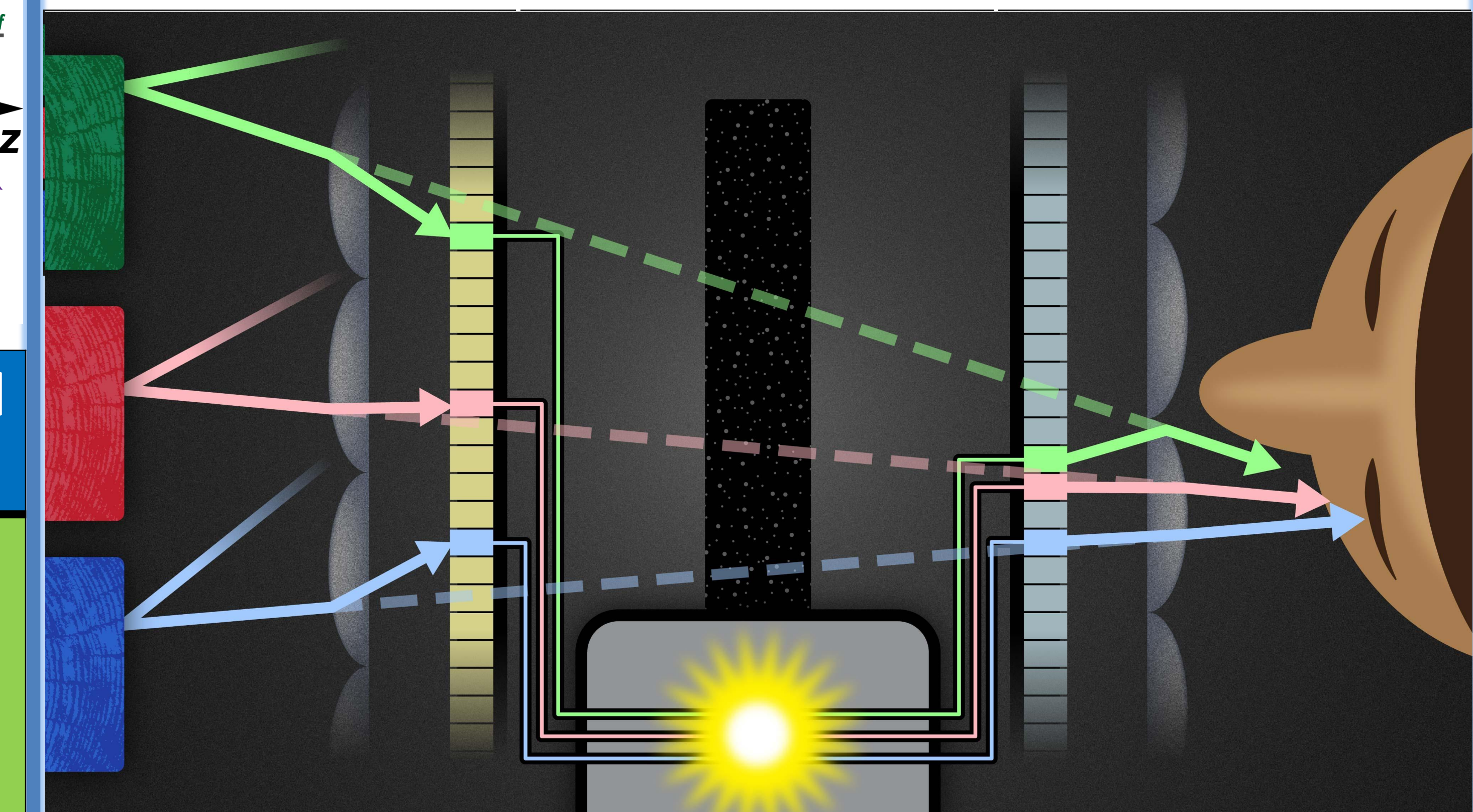
- Simplify to 2D, planar, ray optics:



- To extend to discretized ideal cloak

- **3D:** Use spherical lenslet array (fly’s eye lens array).
- **Phase-matching:** Use corrective plate or spatial light modulator [3].
- **Arbitrary shape:** (z_f, z_i) depends on input and output pixel pair positions.
- **Omnidirectional:** Place emitters and detectors together on closed surface.
- **Wearable cloak:** Sensors and processor can be used for dynamic shapes.

F. “Digital Rochester Cloak” Principle

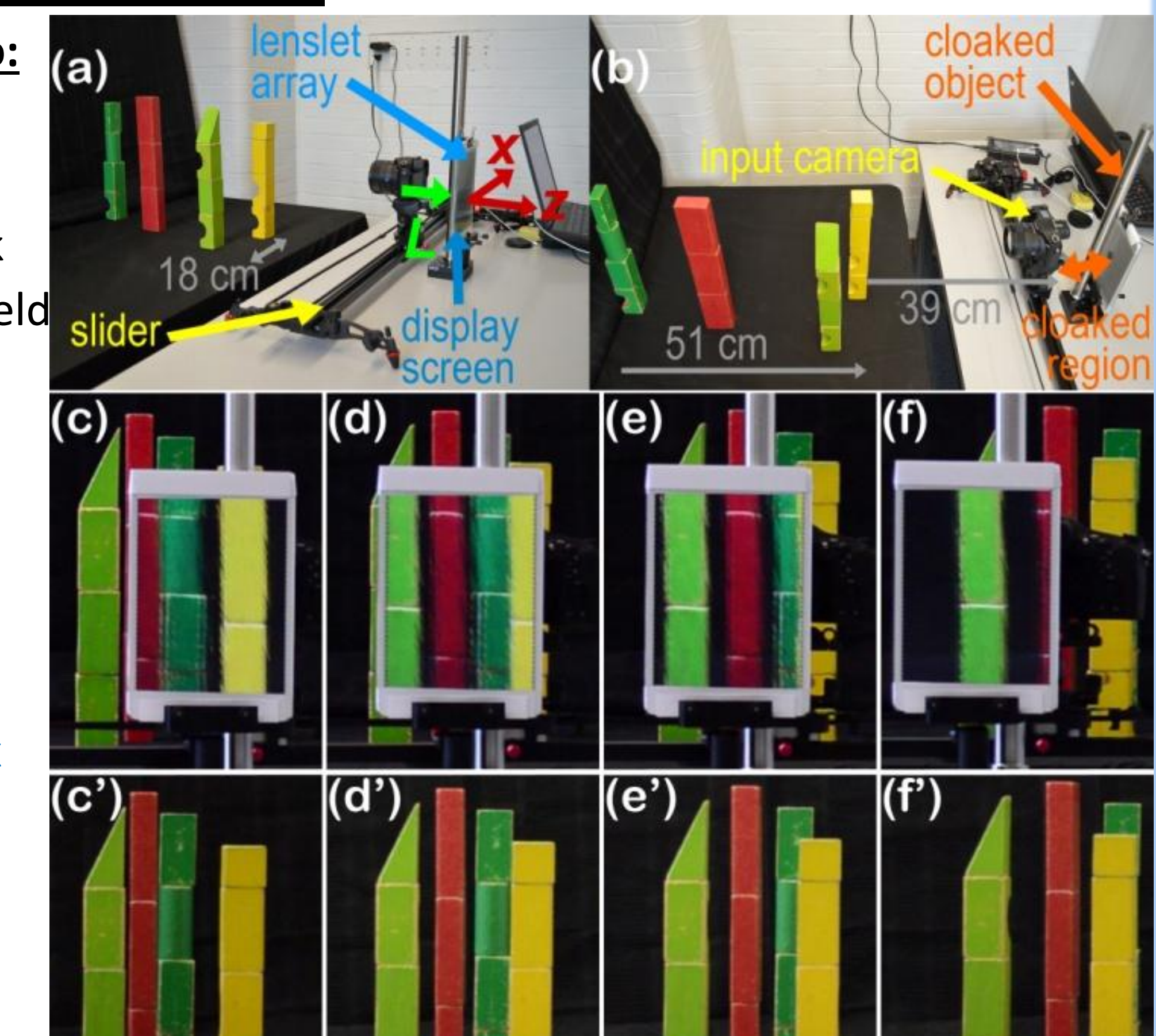


(Mike Osadciw / University of Rochester)

G. Demonstrations

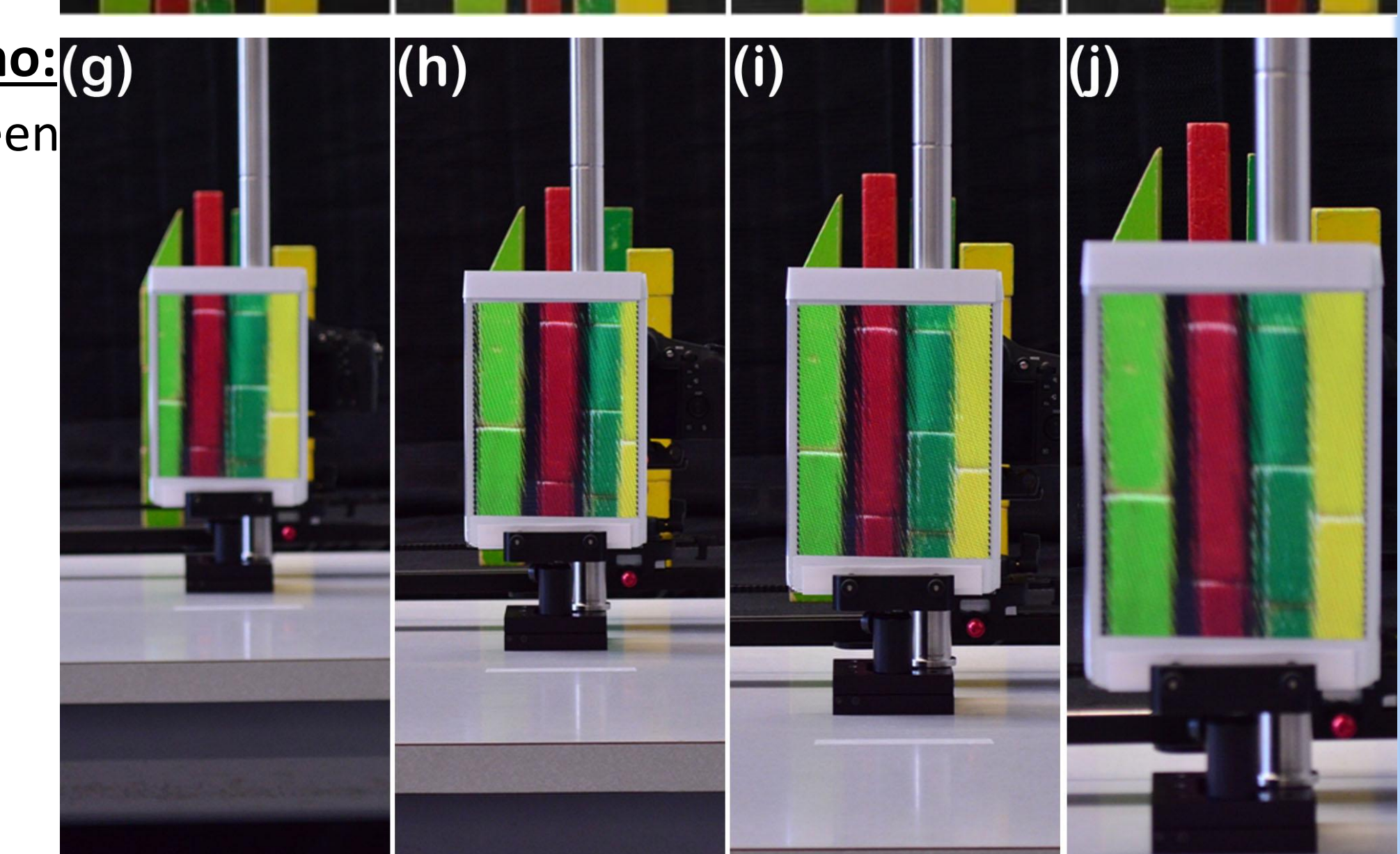
* Horizontal (x) Demo:

- (a)-(b): Setup
- (c)-(f): With cloak
- (c’)-(f’): Without cloak
- 60-90cm depth-of-field
- 29° field-of-view (11° shown)
- 51.5 total “views”
- Output resolution:
 - Angular: 0.56°
 - Spatial: 1.34mm
- Alignment, parallax matched



* Longitudinal(z) Demo:

- Distance/FOV from screen
- (g) 272 cm / 2.53°
- (h) 235 cm / 2.93°
- (i) 203 cm / 3.38°
- (j) 150 cm / 4.59°
- Closer → more seen



H. References

- [1] J. Choi and J. Howell, *Optica* Vol. 3, Issue 5 (2016).
- [2] J. Pendry, D. Schurig, and D. Smith, *Science* 312, 1780 (2006); U. Leonhardt, *Science* 312, 1777 (2006).
- [3] J. Choi and J. Howell, *Opt. Express* 22, 29465 (2014); *Opt. Express* 23, 15857 (2015).
- [4] G. Lippmann, *C. R. Acad. Sci.* 146, 446 (1908).

I. Acknowledgment

Aaron Bauer, Greg Schmidt, University of Rochester Communications (Larry Arbeiter, Matthew Mann, Leonor Sierra, Mike Osadciw, Adam Fenster), UR Ventures.